CS 140 Lecture 17: disk, files

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The present

- A bottom up exposition of file systems
- Disk:

what it looks like some implications

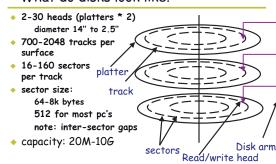
Files:

what they look like why

some implications

 The lecture ignores many other, richer storage system organizations (e.g., databases)

What do disks look like?



main adjectives: BIG, sloowwwwww

Example: a typical disk

- A typical sun disk (two, three years ago)
 1965 cylinders, 17 heads, 80 sec/track, 512 byte sectors
 (1965 * 17 * 80 * 512) / (1024 * 1024) = 1304 MB or about 700,000 double-spaced typewritten pages platter RPM = 3600 RPM (some run at 7200RPM)
- Technology advances mostly in miniaturization in 1975 40Mbytes took up space the size of a washing machine today, my laptop has a 4GB disk.

Disk vs. Memory

- Smallest write: sector
- Atomic write = sector
- Random access: 10ms
 not on a good curve
- Sequential access: 20MB/s
- Cost \$.02MB ('99 PC mag)
- Crash: doesn't matter ("non-volatile")
- (usually) bytes
- byte, word
- 100 ns
 faster all the time
- 200-1000MB/s
- \$1MB
- contents gone ("volatile")

Some useful facts

- Disk reads/writes in terms of sectors, not bytes read/write single sector or adjacent groups
- How to write a single byte? "Read-modify-write"
 read in sector containing the byte
 modify that byte
 write entire sector back to disk
 key: if cached, don't need to read in
- Sector = unit of atomicity.
 sector write done completely, even if crash in middle (disk saves up enough momentum to complete)
 larger atomic units have to be synthesized by OS

Some useful costs

Seek: move disk arm to the right track
best case: Oms (on track already)
worst: ~30-50ms

(move over entire disk)

average: 10-20ms, 1/3 worst case

 Rotational delay: wait for sec to rotate under head best: Oms (over sector)

best: Ums (over sector)
worst: ~16ms (entire rotation)
average: ~8ms (1/2 worst case)

- Transfer bandwidth; suck bits off of device
- Cost of disk access? Seek + rotation + transfer time read a single sector: 10ms + 8ms + 50us ~= 18ms
 Cool: read an entire track? Seek + transfer! (why?)

Some useful trends

- Disk bandwidth and cost/bit improving exponentially similar to CPU speed, memory size, etc.
- Seek time and rotational delay improving *very* slowly why? require moving physical object (disk arm)
- Some implications:

disk accesses a huge system bottleneck & getting worse bandwidth increase lets system (pre-)fetch large chunks for about the same cost as small chunk.

Result? trade bandwidth for latency if you can get lots of related stuff.

How to get related stuff? Cluster together on disk

Memory size increasing faster than typical workload size More and more of workload fits in file cache disk traffic changes: mostly writes and new data

Files: named bytes on disk

File abstraction:

user's view: named sequence of bytes



FS's view: collection of disk blocks
file system's job: translate name & offset to disk blocks
offset:int

disk addr:int

- File operations:
 - create a file, delete a file read from file, write to file
- Want: operations to have as few disk accesses as possible & have minimal space overhead

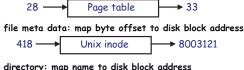
What's so hard about grouping blocks???

 In some sense, the problems we will look at are no different than those in virtual memory

like page tables, file system meta data are simply data structures used to construct mappings.

Page table: map virtual page # to physical page #

directory



→ 3330103

access, files are dense (0 .. filesize-1) & ~sequential ◆ In some way's problem is harder:

• In some ways the problem is easier:

• In some ways problem similar:

FS vs VM

Each layer of translation = potential disk access Space a huge premium! (But disk is huge?!?!) Reason? Cache space never enough, the amount of data you can Get into one fetch never enough.

want location transparency, oblivious to size, & protection

CPU time to do FS mappings not a big deal (= no TLB)

Page tables deal with sparse address spaces and random

Range very extreme: Many <10k, some more than GB. Implications?

Some working intuitions

- FS performance dominated by # of disk accesses
 Each access costs 10s of milliseconds
 Touch the disk 50-100 extra times = 1 *second*
 Can easily do 100s of millions of ALU ops in same time
- Access cost dominated by movement, not transfer
 Can get 20x the data for only ~5% more overhead
 1 sector = 10ms + 8ms + 50us (512/10MB/s) = 18ms
 20 sectors = 10ms + 8ms + 1ms = 19ms
- Observations:

all blocks in file tend to be used together, sequentially all files in a directory tend to be used together all names in a directory tend to be used together How to exploit?

Common addressing patterns

Sequential:

file data processed in sequential order by far the most common mode example: editor writes out new file, compiler reads in file, etc.

Random access:

address any block in file directly without passing through predecessors

examples: data set for demand paging, databases

Keyed access:

search for block with particular values examples: associative data base, index usually not provided by OS

Problem: how to track file's data?

Disk management:

Need to keep track of where file contents are on disk Must be able to use this to map byte offset to disk block The data structure used to track a file's sectors is called a file descriptor

file descriptors often stored on disk along with file

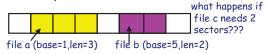
Things to keep in mind while designing file structure:
 Most files are small

Much of the disk is allocated to large files Many of the I/O operations are made to large files

Want good sequential and good random access (what do these require?)

Simple mechanism: contiguous allocation

"Extent-based": allocate files like segmented memory
When creating a file, make the user specify pre-specify
its length and allocate all space at once
 File descriptor contents: location and size



Example: IBM OS/360

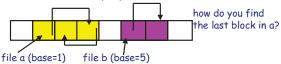
Pro: simple, fast access, both sequential and random.

Cons? (What does VM scheme does this correspond to?)

Linked files

Basically a linked list on disk.

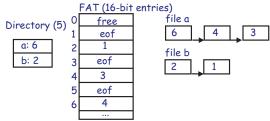
Keep a linked list of all free blocks file descriptor contents: a pointer to file's first block in each block, keep a pointer to the next one



Examples (sort-of): Alto, TOPS-10, DOS FAT

Example: DOS FS (simplified)

Uses linked files. Cute: links reside in fixed-sized
 "file allocation table" (FAT) rather than in the blocks.



Still do pointer chasing, but can cache entire FAT so can be cheap compared to disk access.

FAT discussion

• Entry size = 16 bits

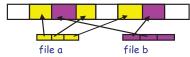
What's the maximum size of the FAT? Given a 512 byte block, what's the maximum size of FS? One attack: go to bigger blocks. Pro? Con?

- Space overhead of FAT is trivial:
 2 bytes / 512 byte block = ~.4% (Compare to Unix)
- Reliability: how to protect against errors?
 Create duplicate copies of FAT on disk.
 State duplication a very common theme in reliability
- ◆ Bootstrapping: where is root directory?

 Fixed location on disk: FAT (opt) FAT root dir ...

Indexed files

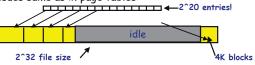
 Each file has an array holding all of it's block pointers (purpose and issues = those of a page table) max file size fixed by array's size (static or dynamic?) create: allocate array to hold all file's blocks, but allocate on demand using free list



pro: both sequential and random access easy con?

Indexed files

Issues same as in page tables

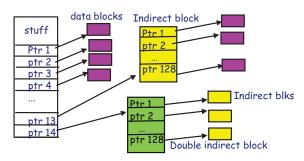


Large possible file size = lots of unused entries Large actual size? table needs large contiguous disk chunk Solve identically: small regions with index array, this array with another array, ... Downside?



Multi-level indexed files: ~4.3 BSD

File descriptor (inode) = 14 block pointers + "stuff"



Unix discussion

- Pro?
 - simple, easy to build, fast access to small files Maximum file length fixed, but large. (With 4k blks?)
- Cons:

what's the worst case # of accesses? What's some bad space overheads?

• An empirical problem:

because you allocate blocks by taking them off unordered freelist, meta data and data get strewn across disk

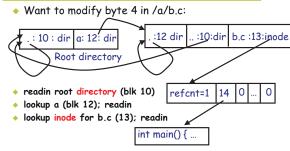
More about inodes

 Inodes are stored in a fixed sized array
 Size of array determined when disk is initialized and can't be changed. Array lives in known location on disk.
 Originally at one side of disk:



The index of an inode in the inode array called an inumber. Internally, the OS refers to files by inumber When file is opened, the inode brought in memory, when closed, it is flushed back to disk.

Example: Unix file system



 use inode to find blk for byte 4 (blksize = 512, so offset = 0 gives blk 14): readin and modify

Turn off comments!

CS 140 Lecture 19: (FS) consistency

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Last time, this time

- ◆ The Big News: Systems crash
 - problem 1: blows away "volatile state" (main memory)
 - problem 2: interrupts updates to "stable state" (disk)
- ◆ Last time:
 - Used state duplication and idempotent actions to create arbitrary sized atomic disk updates.
 - Today: recovery for atomic write
- ◆ This time: Atomicity and consistency in file systems
- ◆ Basic idea:
 - limit error states by updating disk in stylized way
 - after crash run recovery program that knows how to take each error state to a valid state
 - careful: can crash during recovery!

SABRE atomic disk operations

- return D2data; ♦ V1, D1, V2, D2: (different) disk addresses
- ◆ version is a integer in volatile storage
- ◆ a call to atomic-put("seat 25") might result in:
 - { #2, "seat 25", #2, "seat 25" }

If we don't fix after crash, what can happen to make us start using a wrong value? Break into two cases: (1) we are taking last value, does it matter if we corrupt? (Only recycle version) (2) if we are using first? (yupper)

Does it work?

- Assume we have correctly written to disk:
 - { #2, "seat 25", #2, "seat 25" }
- ◆ And that the system has <u>crashed during the operation</u> atomic-put("seat 31")

 Could crash and get in good state again 2-3-4
- There are 6 cases, depending on where we failed in

```
atomic-put: Actually, this isn't true: what other cases are there? (failure betweent)

put # fails possible disk contents atomic-get returns?

before {#2, "seat 25", #2, "seat 25"}

the first {#2.5, "seat 25", #2, "seat 25"}

the second {#3, "seat 35", #2, "seat 25"}

the third {#3, "seat 31", #2.5, "seat 25"}

the fourth {#3, "seat 31", #3, "seat 35"}

[Error if crash on version model of the fourth {#3, "seat 31", #3, "seat 31"}
```

Recovery: built on idempotent operations

```
void recover(void) {
  V1data := get(V1); # following 4 ops same as in a-get
  D1data := get(D1);
  V2data = get(V2);
  D2data := get(D2);
  if (V1data == V2data)
      if(D1data |= D2data)
         # if we crash & corrupt D2, will get here again.
         put(D1data, D2); Is it ok to corrupt d2?
 e se
      #if we crash and corr<u>upt D1 will get b</u>ack here
      put(D2data, D1);
                             Is it ok to corrupt d1?
      #if we crash and corrupt V1, will get back here
     put(V2data, V1);
                             Is it ok to corrupt v1?
  version = V1data
```

The power of state duplication

- Most approaches to tolerating failure have at their core a similar notion of state duplication
 - Want a reliable tire? Have a spare
 - Want a reliable disk? Keep a tape backup. If disk fails, get data from backup. (Make sure not in same building.)
 - Want a reliable server? Have two, with identical copies of the same information. Primary fails? Switch. (Make sure not on same side of the country)
 - Like caches (another state duplication): easy to generalize to more (have 'n' spares)

Fighting failure

- In general, coping with failure consists of first defining a failure model composed of
 - Acceptable failures. E.g., the earth is destroyed by weirdos from Mars. The loss of a file viewed as unavoidable.
 - Unacceptable failures E.g. power outage: lost file not ok
- Second, devise a recovery procedure for each unacceptable failure:
 - takes system from a precisely understood but incorrect state to a new precisely understood and correct state.
- Dealing with failure is *hard*
 - Containing effects of failure is complicated.
 - How to anticipate everything you haven't anticipated?

The rest today: concrete cases

- ◆ What happens during crash happens during
 - creating, moving, deleting, growing a file?
- ◆ Woven throughout: how to deal with errors
 - the simplest approach: synchronous writes + fsck

Synchronous writes + fsck

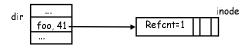
- ◆ Synchronous writes = ordering state updates
 - to do n modifications: write block 1 Wait for disk
 write block 2 Wait for Wait for disk
 - simple but slowwww
- ◆ fsck:
 - after crash, sweep down entire FS tree, finding what is broken and try to fix.
 - Cost = O(size of FS). Yuck.

Unix file system invariants

- ◆ File and directory names are unique
- ◆ All free objects are on free list
 - + free list only holds free objects
- ◆ Data blocks have exactly one pointer to them
- ◆ Inode's ref count = the number of pointers to it
- All objects are initialized
 - a new file should have no data blocks, a just allocated block should contain all zeros
- ◆ A crash can violate every one of these!

File creation

- ◆ open("foo", O_CREAT|O_RDWR|O_EXCL)
 - 1: search current working directory for "foo"
 » if found, return error (-EEXIST)
 - » else find an empty slot
 - 2: Find a free inode & mark as allocated.
 - 3: Insert ("foo", inode #) into empty dir slot.
 - 4: Write inode out to disk



• Possible errors from crash?

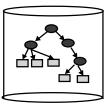
Unused resources marked as "allocated"

- If free list assumed to be Truth, then many write order problems created.
 - Rule:never persistently record a pointer to any object still on the free list
- Dual of allocation is deallocation. The problem happens there as well.
- ◆ Truncate:
 - 1: set pointer to block to 0
 - 2: put block on free list
 - if the writes for 1 & 2 get reversed, can falsely think something is freed
 - Dual rule: never reuse a resource before persistently nullifying all pointers to it.

Does a cycle matter? If we can have links to files, does this create cycles? What does?

Reactive: reconstruct freelist on crash

- ◆ How?
 - Mark and sweep garbage collection!
 - Start at root directory
 - Recursively traverse all objects, removing from free list



- Good: is a fixable error. Also fixes case of allocated objects marked as free.
- Bad: Expensive, requires traversing all live objects and makes reboot slowwww.

Pointers to uninitialized data

- Crash happens between the time pointer to object recorded and object initialized
- ◆ Uninitialized data?
 - Security hole: Can see what was in there before
 - Most file systems allow this, since expensive to prevent
- ◆ Much worse: Uninitialized meta data
 - Filled with garbage. On a 4GB disk, what will 32-bit garbage block pointers look like?
 - Result: get control of disk blocks not supposed to have
 - *Major* security hole.
 - inode used to be a real inode? can see old file contents
 - inode points to blocks? Can view/modify other files

Cannot fix, must prevent

- ◆ Our rule:
 - never (persistently) point to a resource before it has been initialized
- ◆ Implication: file create 2 or 3 synchronous writes!
- Write 1: Write out freemap to disk. Wait.
- Write 2: Write out 0s to initialize inode. Wait.
- Write 3: write out directory block containing pointer to inode. (maybe) Wait. (Why?)

Deleting a file

- ◆ Unlink("foo")
 - 1: traverse current working directory looking for "foo"
 - » if not there, or wrong permissions, return error
 - 2: clear directory entry
 - 3: decrement inode's reference count
 - 4: if count is zero, free inode and all blocks it points to
- ◆ what happens if crash between 2&3, 3&4, after 4?

Could have thought you'd deleted a file, but after a crash it comes back.:

Bogus reference count

- Reference count to high?
 - inode and its blocks will not be reclaimed
 » (2 gig file = big trouble)
 - what if we decrement count before removing pointer?
- ◆ Reference count too low
 - real danger: blocks will be marked free when still in use
 - major security hole: password file stored in "freed" blocks.
 - Reactive: fix with mark & sweep
 - Proactive: Never decrement reference counter before nullifying pointer to object.

R=1

Proactive vs reactive

- ◆ Proactive:
 - pays cost at each mutation, but crash recovery less expensive.
 - E.g., every time a block allocated or freed, have to synchronously write free list out.
- ◆ Reactive: assumes crashes rare:
 - Fix reference counts and reconstruct free list during recovery
 - Eliminates 1-2 disk writes per operation

Growing a file

- write(fd, &c, 1)
 - translate current file position (byte offset) into location in inode (or indirect block, double indirect, ...)
 - if meta data already points to a block, modify the block and write back
 - otherwise: (1) allocate a free block, (2) write out free list, (3) write out block, (4) write out pointer to block
- ◆ What's bad things a crash can do?
- What about if we add block caching?
 - "write back" cache? Orders can be flipped!
 - What's a bad thing to reverse?

Moving a file

- mv foo bar (assume foo → inode # 41)
 - lookup "foo" in current working directory
 - » if does not exist or wrong permissions, return error
 - lookup "bar" in current working directory
 if wrong permissions, return error
 - 1: nuke ("foo", inode 41)
 - 2: insert ("bar", inode 41)
 - crash between 1 & 2?
 - what about if 2 and 1 get reordered?

Conservatively moving a file

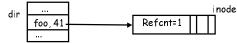
- ◆ Rule:
 - never reset old pointer to object before a new pointer has been set
- → mv foo bar (assume foo -> inode # 41)
 - lookup foo in current working directory
 - » if does not exist or wrong permissions, return error
 - lookup bar in current working directory
 - » if wrong permissions return error
 - 0: increment inode 41's reference count. Wait.
 - 1: insert ("bar", inode 41). Wait
 - 2: nuke ("foo", inode 41) Wait
 - 3: decrement inode 41's reference count
- ◆ costly: 3 synchronous writes! How to exploit fsck?

Summary: the two fixable cases

- ◆ Case 1: Free list holds pointer to allocated block
 - cause: crash during allocation or deallocation
 - rule: make free list conservative
 - free: nullify pointer before putting on free list
 - allocate: take off free list before adding pointer
- ◆ Case 2: Wrong reference count
 - too high = lost memory (but safe)
 - too low = reuse object still in use (very unsafe)
 - cause: crash while forming or removing a link
 - rule: conservatively set reference count to be high
 - unlink: nullify pointer before reference count decrement
- link: increment reference count before adding pointer
 Alternative: ignore rules and fix on reboot.

Summary: the two unfixable cases

- ◆ Case 1: Pointer to uninitialized (meta)data
 - rule: initialize before writing out pointer to object create("foo"): write out inode before dir block



- growing file? Typical: Hope crashes are rare...
- ◆ Case 2: lost objects
 - rule: never reset pointer before new pointer set
 - mv foo bar: create link "bar" before deleting link "foo." crash during = too low refent, fix on reboot.

4.4 BSD: fast file system (FFS)

- ◆ Reconstructs free list and reference counts on reboot
- ◆ Enforces two invariants:
 - directory names always reference valid inodes
 - no block claimed by more than one inode
- ◆ Does this with three ordering rules:
 - write newly allocated inode to disk before name entered in directory
 - remove directory name before inode deallocated
 - write deallocated inode to disk before its blocks are placed on free list
- ◆ File creation and deletion take 2 synchronous writes
- ◆ Why does FFS need third rule? Inode recovery

FFS: inode recovery

- Files can be lost if directory destroyed or crash happens before link can be set
 - New twist: FFS can find lost inodes
- ◆ Facts:
 - FFS pre-allocates inodes in known locations on disk
 - Free inodes are to all Os.
- ♦ So?
 - Fact 1 lets FFS find all inodes (whether or not there are any pointers to them)
 - Fact 2 tells FFS that any inode with non-zero contents is (probably) still in use.
 - fsck places unreferenced inodes with non-zero contents in the lost+found directory

Fsck: reconstructing file system

```
# mark and sweep + fix reference counts
worklist := { root directory }
while e = pop(worklist) # sweep down from roots
  foreach pointer pine
      # if we haven't seen p and p contains pointers, add
      if p.type != Block and !seen{p}
            push(worklist, p);
                               # p's notion of pointers to i
            refs{p} = p.refcnt;
                                 # count references to p
      seen{p} += 1;
      freelist[p] = ALLOCATED; # mark not free
foreach e in refs
                                 # fix reference counts
   if(seen{e} != refs{e})
      assert(p.type.has_refcnt); # shouldn't happen
      e.refcnt = seen{e};
      e.dirty = true;
```

Write ordering

- ◆ Synchronous writes expensive
 - sol'n have buffer cache provide ordering support
- Whenever block "a" must be written before block "b" insert a dependency



- Before writing any block, check for dependencies
- (when deadlock?)
- To eliminate dependency, synchronously write out each block in chain until done.
 - Block B & C can be written immediately
 - Block A requires block B be synchronously written first.

CS 140 Lecture 20: SPEED! SPEED! SPEED!

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Past, Present & Future

- Recent past:
 - dealing with failure.
- Recent present (today):
 - dealing with huge disk latencies
- Recent future (monday):
 - dealing with reality: actual file systems dealing with multiple disks (raid)
- Further future:
 - next week: networking
- Readings (all on course web page):
 - A Fast File System for UNIX (paper)
 - Unix implementation paper

Sucking + blowing data through slow straws

Latency tricks

Caching (data centric) Code migration (code centric)

Prefetching (dual: asynchronous writes)

Clever data layout

Throughput tricks:

Increase bandwidth? Duplicate device N times Hide latency? Run another thread while waiting

"Money can buy bandwidth. Latency requires bribing God."

These tricks are eternal themes

use whenever need fast access to data living in slow place common straws: I/O bus, memory bus, network, space (bi-directional), time (uni-directional)

Caching: the buffer cache

Our cliché: past predicts future? Use a cache.



- Buffer cache roughly similar to page cache good: memory growth on similar curve as disk capacity
- bad: forces 2 copies for normal interface; "cache wiping"
- Our timeless cache questions: How big? How to evict? What happens to writes? What to prefetch?

Decision #1: Size

How big to make cac he?

Main issue: partitioning memory buffer cache and VM page cache (its main competitor)

Early systems: fixed-size cache.

Problem: doesn't adapt to workload.

Obvious sol'n: variable sized cache

Blks 6 MB

4 MB

Problem: enormous files not uncommon.

Solution: fixed size caches?

Same problem sharing page cache across "n" users. Solve in same way (with the same slide!)

Split versus shared caches

Private caches

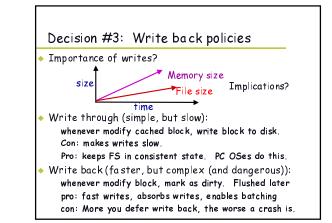
block cache and page cache have a separate pool of pages miss in one can only replace one of its own pages isolates cache, preventing interference

poolbarrier Blks (4MB) Pages (4MB)

BUT: prevents one cache from using other's (comparatively) idle resources

efficient memory usage needs way to (slowly) change the allocations to each pool. Usually keep a fixed reserve Qs: What is "slowly"? How big a pool? When to migrate?

Decision #2: Eviction policy * "Dance with the one that brought you" The reason we used a cache was because past ~ future. So use LRU (as usual). New twist: can have perfect LRU! New twist #2: Unfortunately, now it's less of a good idea since many files much bigger than VM objects. * What to do when file larger than cache? LRU = exact worse thing. !LRU = best thing! (MRU) File has 4 blocks 1 2 3 4 Reference strings 1234 # of faults for 3 block cache?



Write back complications

Fundamental tension:

On crash, all modified data in cache is lost. Longer you postpone write back, the worst the damage is, but the faster you are.

Four times to flush:

when block evicted (this is ~ what VM does)
when a file is closed (distributed file systems do this)
on an explicit flush ("man sync")
when a time interval elapses (30 secs in Unix)

- Write back doesn't respect ordering crash = file in weird jumbled state
- Finally: OS may not have any choice!
 Disk could be doing write buffering.

Flushing nuance: All blocks are not equal

Losing some blocks worse than losing others. Usually:

File system effects:

flush modified meta data
back quickly

Note: was an implicit

superblock

directory

inode

Data black

side-effect of synchronous writes for meta data mods

importance

Application effects:

have a really important file? Issue a manual flush (sync) to make sure its saved to disk.

Databases can forced to do this. Frequently, they will just by-pass file system.

Decision #4: what to prefetch?

 Optimal: the blocks we need are fetched in just enough time for us to use them.

Note: if we had enough disk bandwidth and ability to predict future wouldn't need (much of) a cache: just fetch block that will be used, and then throw way.

Example:

App issues reads disk block every 1ms Disk can accept new request every 1ms Each request takes 10ms to satisfy How big a cache do we need?

The usual problem: we don't know the future.
 (Cache = trade space for stupidity)

Location ~ future ("Spatial locality")

"Spatial local ity"

Access one object, will probably access ones close to it E.g., read logical block in file, probably read next too. So, when get one block, get the next n that follow.

More precise: when access one object, will probably access ones *related* to it. So, cluster them, and use above scheme.

How big is "n"?

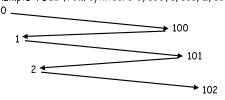
Tradeoff: larger n means more payoff if we are right, but more wastage if not. (Usually n < 65k bytes) Variant: get big chunks & preferentially discard

Decision #5: scheduling disk arm

- One resource, multiple requests = scheduling problem one disk arm, multiple read and write requests
- ♦ Goals?
 - minimize seeks no starvation
- Disk scheduling algorithms have close analogues in process scheduling
 - and, similarly, become more important as more requests. (However, unlike job queue, disk queue usually short...)
- Next: three scheduling variations
 - optimize seek times
 - newer disks require taking account of rotational delay

First-come-first-served

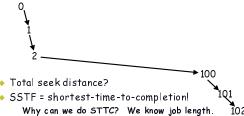
- Schedule disk requests in order received.
 Fair but may have huge seeks for no good reason.
- Example: read from cylinders 0, 100, 1, 101, 2, 102



total seek distance?

Shortest seek time first

- Handle nearest request first
- optimize disk arm movement, but can be (really) unfair
- Example: read from cylinders 0, 100, 1, 101, 2, 102



Scan (elevator algorithm)

- Move arm back & forth, handling requests underneath more fair to requests scattered across disk, similar performance to SSTF
 - Example: read from cylinders 0, 100, 1, 101, 2, 102
- ◆ Total seek distance?
- ◆ works well when many requests
 - if not many, about 1/2 time won't get shortest seek

Original Unix File System

- Simple and elegant:
- inodes data blocks (512 bytes)
- superblock
- ♦ Nouns:
 - data blocks
 - inodes (directories represented as files)
 - hard links
 - superblock. (specifies number of blks in FS, counts of max # of files, pointer to head of free list)

disk

- Problem: slow
 - only gets 20Kb/sec (2% of disk maximum) even for sequential disk transfers!

A plethora of performance costs

- Blocks too small (512 bytes)
 - file index too large
 - too many layers of mapping indirection transfer rate low (get one block at time)
- Sucky clustering of related objects:
 - Consecutive file blocks not close together
 - Inodes far from data blocks
 Inodes for directory not close together
 - poor enumeration performance: e.g., "Is", "grep foo *.c"
- Next: how FFS fixes these problems (to a degree)

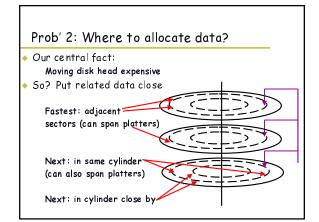
Problem 1: Too small block size

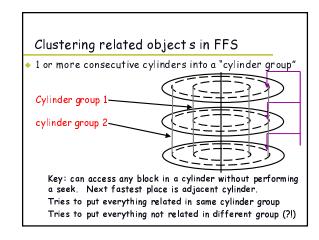
Why not just make bigger?

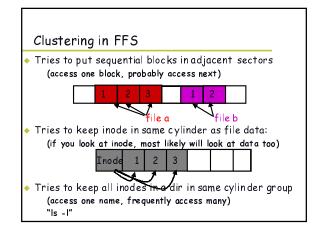
Block size	space wasted	file bandwidth
512	6.9%	2.6%
1024	11.8%	3.3%
2048	22.4%	6.4%
4096	45,6%	12,0%
1MB	99.0%	97.2%

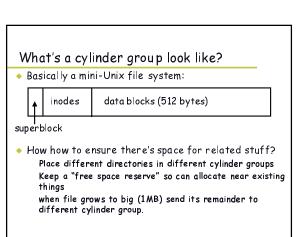
 Bigger block increases bandwidth, but how to deal with wastage ("internal fragmentation")?
 Use idea from malloc: split unused portion.

Handling internal fragmentation BSD FFS: has large block size (4096 or 8192) allow large blocks to be chopped into small ones ("fragments") Used for little files and pieces at the ends of files Best way to eliminate internal fragmentation? Variable sized splits of course Why does FFS use fixed-sized fragments (1024, 2048)?



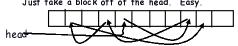






Prob' 3: Finding space for related objects

Old Unix (& dos): Linked list of free blocks
 Just take a block off of the head. Easy.



 $\mbox{Bad: free list gets jumbled over time. Finding adjacent blocks hard and slow$

Using a bitmap

- Usually keep entire bitmap in memory:
 46 disk / 4K byte blocks. How big is map?
- Allocate block close to block x?
 check for blocks near bmap[x/32]
 if disk almost empty, will likely find one near
 as disk becomes full, search becomes more expensive and
 less effective
- Trade space for time (search time, file access time)
 keep a reserve (e.g, 10%) of disk always free, ideally
 scattered across disk
 don't tell users (df --> 110% full)
 N platters = N adjacent blocks
 with 10% free, can almost always find one of them free

So what did we gain?

- Performance improvements:
 able to get 20-40% of disk bandwidth for large files
 10-20x original Unix file system!
 Better small file performance (why?)
- Is this the best we can do? No.
- Block based rather than extent based name contiguous blocks with single pointer and length (Linux ext2fs)
- Writes of meta data done synchronously really hurts small file performance make asynchronous with write-ordering ("soft updates") or logging (the episode file system, ~LFS) play with semantics (/tmp file systems)

RAID: exploiting multiple disks

- "Redundant array of inexpensive disks" (acronym from same people that named RISC)
- Empirical observation:

to get given capacity much cheaper to buy n small disks than 1 large one.

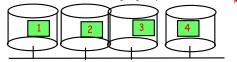
Once you buy multiple disks, can do some neat tricks

- Trick 1: n-fold bandwidth increase (ideal)
 stripe data across multiple disks
 read/write from all simultaneously
 (common theme: money buys bandwidth by buying multiple
 straws (networks, disks, highway lanes,...))
- Trick 2: use to increase reliability
 keep copies of data on different disks. Switch on failure

Theme 1 in RAID: Major bandwidth

Striping: smear data across all disks.
 Ideal: N reads/writes going in parallel

"RAID O"



- Basic idea: straw too thin? Buy more of them and suck in parallel.
- Problem: reliability.

N disks, probability that one blows up increases as well. Independent failures? 100 disks = 100 more likely that one is down. MTTF of 200K hrs/100 = $2Khrs \sim 3months$

Theme 2 in RAID: Reliability

Mirroring: improves reliability (and read performance)

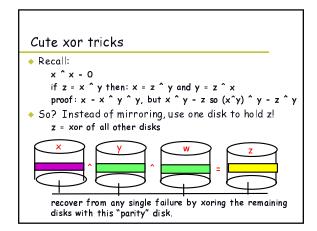


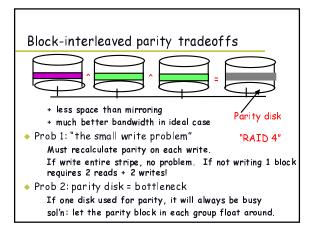


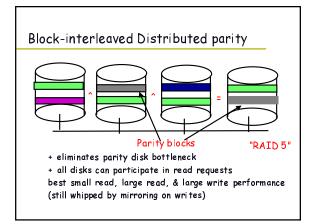
"RAID 1"

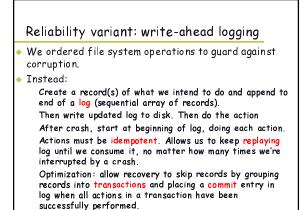
every read/write operation issued to both disks

- Basic idea (seen before):
 - duplicate state to increase reliability
- Like backups except:
 - copy is completely up to data
 - "crossover" is fast
 - fault-tolerant systems use this basic trick a lot









Example: write -ahead logging to create a file foo.c write two log records write ("foo", 51) @ byte 30 in blk 319 # create link write 0s into blk 51 # initialize inode Log grows downward Write log to disk. Then modify cached copies of blks 319 and 51. After these written to disk, write

Key: brute writes are always idempotent.

E.g., can repeat "i = 5" as often as you want

What have we gained? Result 1: freedom from ordering tyranny If log holds records for many dependencies, a single disk write eliminates many sequential dependencies. Can then write blocks containing actual directories and inodes in any order (key: don't have to wait 10ms before writing the next) Result 2: fast recovery Rather than scan entire disk checking for errors, just reply log. Much much faster the episode file system does this. Result 3: compressed dependency representation if the machine has small amount of non-volatile RAM, keep log in it. Potentially eliminate *all* ordered writes!